Matrix Project Due on Fri, Jul 18

Let us numerically solve $A\vec{x} = \vec{b}$ with Gaussian-Jordan elimination. Here A is an $n \times n$ matrix and \vec{b} is a vector with n components. We will write a numerical code to obtain \vec{x} .

To consider the algorithm, we begin with the following example. Suppose we have a system of equations

$$\begin{cases} 2x_1 - x_2 &= 1, \\ -x_1 + 2x_2 - x_3 &= 0, \\ -x_2 &+ 2x_3 &= 1. \end{cases}$$

We write the augmented matrix as

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & b_1 \\ a_{21} & a_{22} & a_{23} & b_2 \\ a_{31} & a_{32} & a_{33} & b_3 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 & 1 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & 1 \end{bmatrix}.$$

By (2nd row) $-\frac{a_{21}}{a_{11}}(1st row)$, we obtain

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & b_1 \\ 0 & a_{22} - m_{21}a_{12} & a_{23} - m_{21}a_{13} & b_2 - m_{21}b_1 \\ 0 & a_{32} & a_{33} & b_3 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 & 1 \\ 0 & \frac{3}{2} & -1 & \frac{1}{2} \\ 0 & -1 & 2 & 1 \end{bmatrix},$$

where $m_{21} = a_{21}/a_{11} = -1/2$. Now we have

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & b_1 \\ 0 & a_{22} & a_{23} & b_2 \\ 0 & a_{32} & a_{33} & b_3 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 & 1 \\ 0 & \frac{3}{2} & -1 & \frac{1}{2} \\ 0 & -1 & 2 & 1 \end{bmatrix}.$$

By (3rd row) $-m_{32}$ (2rd row), where $m_{32} = a_{32}/a_{22} = -1/\frac{3}{2} = -2/3$, we obtain

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & b_1 \\ 0 & a_{22} & a_{23} & b_2 \\ 0 & a_{32} - m_{32}a_{22} & a_{33} - m_{32}a_{23} & b_3 - m_{32}b_2 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 0 & 1 \\ 0 & \frac{3}{2} & -1 & \frac{1}{2} \\ 0 & 0 & \frac{4}{3} & \frac{4}{3} \end{bmatrix}.$$

Thus we obtain the upper triangular matrix

	a_{22}	a_{13} a_{23} a_{33}	b_2	=	_	_	0 -1 $\frac{4}{3}$ -1	$\frac{1}{\frac{1}{2}}$,
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or the system

$$\begin{cases} 2x_1 - x_2 &= 1, \\ \frac{3}{2}x_2 - x_3 &= \frac{1}{2}, \\ \frac{4}{3}x_3 &= \frac{4}{3}. \end{cases}$$

The matrix is not in reduced row-echelon form but we will find below that this triangular matrix is enough.

We implement Gauss-Jordan elimination by generalizing the above example. An upper triangular matrix (row-echelon form) is obtained as follows.

```
1 for k=1:n-1 % k: step index
2 for i=k+1:n
3 m(i,k)=a(i,k)/a(k,k)
4 for j=k+1:n
5 a(i,j)=a(i,j)-m(i,k)*a(k,j)
6 end
7 b(i)=b(i)-m(i,k)*b(k)
8 end
```

We note that $a_{kk} \neq 0$ is assumed¹.

Now A is an upper triangular matrix. In general we have

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= b_1 \\ a_{22}x_2 + \dots + a_{2n}x_n &= b_2 \\ \vdots \\ a_{nn}x_n &= b_n \end{cases}$$

¹Although we assume $a_{kk} \neq 0$ for our project, sometimes $a_{kk} = 0$ or a_{kk} becomes very close to 0. If $a_{kk} = 0$, then we can find index l such that $|a_{lk}| = \max\{|a_{ik}| : k \leq i \leq n\}$, interchange the lth row and kth row, and proceed with the elimination. If A is invertible, then Gauss-Jordan elimination with this swap process (partial pivoting) does not break down (Math 571).

We can readily obtain $x_n, x_{n-1}, \ldots, x_1$ by back substitution:

$$x_{n} = \frac{b_{n}}{a_{nn}},$$

$$x_{n-1} = \frac{b_{n-1} - a_{n-1,n}x_{n}}{a_{n-1,n-1}},$$

$$\vdots$$

$$x_{1} = \frac{b_{1} - (a_{12}x_{2} + \dots + a_{1n}x_{n})}{a_{11}}.$$

This procedure can be implemented as follows.

```
1 || x(n)=b(n)/a(n,n)
2 | for i=n-1:-1:1 % i: row index
3 | tmp=b(i)
4 | for j=i+1:n % j: column index
5 | tmp=tmp-a(i,j)*x(j)
6 | end
7 | x(i)=tmp/a(i,i)
8 || end
```

In this way we can solve $A\vec{x} = \vec{b}$ and obtain the solution vector \vec{x} .